KaGErOFU: Kanazawa University Gamma-ray Burst Explorer for **Optical Flash Understanding**

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1. background

- **Gamma-ray burst GRB**
- **O** properties
- Extremely high-energy explosion ~10⁵²erg
- **Transient event**
- **Observable across** multiple wavelengths



O Radiation mechanism of prompt emission

- Internal shock model
- Photospheric model

polarization observations of gamma rays \Rightarrow the internal shock model?

4.Gound test for evaluating imaging performance

Night observation

Olnvestigation of the feasibility of imaging a 7th magnitude star

- Captured with varying exposure
- targeting Vega in the field of view on the rooftop of Kanazawa University.





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certain spectra remain unexplained \Rightarrow investigate with multi-wavelength

Optical flash

- Rare optical event during the prompt emission
- The origin theory is competed Synchrotron emission or Reverse shock during initial afterglow



After confirming the position of Vega using the Windows camera viewer software, the image was captured using BBM

Star extraction

OUsing DAOStarFinder from photutils

Set the threshold for identifying stars and the Full Width at Half Maximum (FWHM) to define the spread of pixels considered as a star.



2.KaGErOFU

Kanazawa University Gamma-ray Burst Explorer for Optical Flash Understanding

Spin-off from the MeV gamma-ray galactic plane survey project SMILE-3 \Rightarrow Application from subsystems to mission equipment

Mission goal

Multiple star camera systems are mounted on a super-pressure balloon, and aim to observe several examples of optical flash

Takada

Balloon release during

SMILE-2+ experience

Oadvantage **Compared to ground observations:**

- Ascends to altitudes of 20 to 50 km
- Atmospheric effects reduced to less than 5%
- Not affected by ground weather conditions **Compared to satellite observations:**
- Reduced cost and operational resources
- Capable of long-duration observations

OObjective of development

⇒Poster 97 : Study on Piggyback Balloon Experiment of Star Camera System for SMILE-3 Project

3.Star camera BBM

 $O5 \times 5$ photometry on the extracted stars **2ADC vs. magnitude** Fit: $a \times log(10)ADC + b$ 8.0 Data with error 7.5 7.0 gnitude 9 6.0 5.5



Sencer and lense



 2/3" Sony CMOS Pregius IMX264sencer The Imaging Source DFK33UX264 sencer size : 8.4456mm × 7.0656mm (2448pix × 2048pix)

tps://www.argocorp.com/cam/usb3/tis/DxK33UX264.html



• FUJINON HF25SA-1

- aperture: 50mm
- focal length : 25mm

https://www.fujifilm.com/jp/ja/business/optical-devices/mvlens/hfsa#model02

5.Summary and future



Raspberry Pi



- Photometric performance of the star camera BBM is consistent with radiant flux determined by AB magnitude within 0.2 magnitude under room temperature and atmospheric pressure.
- Detection of stars up to approximately magnitude 9 has been confirmed. This suggests the possibility of detecting optical flashes, such as those observed in past GRBs (e.g., GRB 990123: ~10 mag, GRB 080319B: ~5.5 mag)

The KaGErOFU, developed as a scientific extension of the star camera subsystem from the SMILE-3 experiment, has been initiated. Ultimately, the goal is to mount multiple camera systems on a super-pressure balloon and observe several examples of optical flashes. For principle validation, a piggyback test using only the star camera system is planned for the next fiscal year. This test will investigate the overall system's operational performance at balloon altitude due to scattered light from Earth. At present, it has been confirmed that, under room temperature and atmospheric pressure conditions, the photometric performance of the star camera BBM is consistent with radiant flux determined by AB magnitude within 0.2 magnitude, and cover the magnitudes of past optical flashes. In preparation for the piggyback test, we plan to fabricate an electronics board for the automated imaging system and conduct thermal-vacuum tests on the system. A matching script using the Hipparcos Catalogue is under development, with the goal of achieving direction determination accuracy of less than 0.5° for the camera's central field of view.

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